# Carlos Gutiérrez Álvarez

## PhD Student in Artificial Intelligence & Robotics

Universidad de Alcalá, Campus Universitario, A2 Km 33.600 28805, Alcalá de Henares, Spain

Education	
University of Alcalá	Alcalá de Henares, Spain
• Advisor: Dr. Roberto J. López Sastre	2021 - present
Complutense University of Madrid	Madrid, Spain
MSc in Mathematical Engineering  • Thesis: "BERT for Question Answering"	2018 - 2019
Complutense University of Madrid	Madrid, Spain
BSc in Physics	2014 - 2018
Honors thesis	
Professional Experience	
University of Alcalá	Madrid, Spain
SPANISH SCIENCE MINISTRY PRE-DOCTORAL SCHOLARSHIP	Sep. 2021 - Present
<ul> <li>Doctoral Thesis: "Reinforcement Learning for Visual Semantic Navigation"</li> <li>Working with a FPI scholarship by Spanish Science Ministry.</li> </ul>	

Accenture TechnologyMadrid, SpainSENIOR AI ENGINEERFeb. 2019 - Sep. 2021

- Development of cognitive systems: Virtual assistants, NLP and Image Recognition.
- Development of a telephonic virtual assistant for one of the biggest Spanish electrical companies including:

Design of custom NLP neural architectures in Tensorflow.

CI/CD using Jira's suite and agile methodologies in AWS.

Design of workflows and reporting using Kibana and ElasticSearch.

Design of conversational flows using RASA.

Deployment of the whole system in AWS via Kubernetes.

• Implementation of Salesforce Einstein solutions for CRMs.

Banco SantanderLas Rozas, SpainPLANNIFICATION ASSISTANTJune 2018 - Feb 2019

- Part of the Planning, Productivity and Quality department at Banco Santander, where we mainly make predictions for the working curves for different front and back office services.
- Development and improvement of company's reports and digital tools in cooperation with IT department.
- Collaboration with business, front and back office areas in designing pilot processes for efficiency improvements.
- Improvement of data acquisition and analysis in collaboration with IT department.
- Collaboration with business areas in the development of SLAs and KPIs related to the planning, adhesion, and efficiency of the services.
- Design and acquisition of quality reports using QlikView.

Research Exp	orionco		
Research Exp	enence		

# University of Alcalá - Dept of Telecommunications and Signal Theory

Madrid, Spain

ADVISOR: DR. ROBERTO JAVIER LÓPEZ SASTRE

Sep. 2021 - Present

- · Development of reinforcement learning agents for visual semantic navigation in indoor environments.
- Integration of robotic platforms to help children with functional diversity.
- Implementation of artificial intelligence solutions over robotic platforms using ROS.
- Use of Embodied AI techniques to improve the interaction between robots and its environment.
- Development of offline reinforcement learning algorithms to improve the learning process from pre-recorded datasets.

## **Tokyo Institute of Technology - Dept of Computer Science**

Tokyo, Japan

ADVISOR: DR. ASAKO KANEZAKI

March. 2024 - Present

- Offline reinforcement learning for robotic navigation tasks.
- Exploration of meta reinforcement learning solutions for the sim-to-real gap in real robots.
- Use of TSUBAME 4.0 supercomputer for training deep reinforcement learning models.

# **Complutense University of Madrid - Dept of Nanomaterials**

Madrid, Spain

ADVISOR: DR. RAFAEL PEREZ

Dec. 2017 - June 2018

- Collaboration with the Nanomagnetism and Magnetization Processes Group at the Institute of Materials Science of Madrid (ICMM).
- Development of  $Fe_{90}Si_5B_5$  alloys using voltaic arc melter.
- Production of microwires by the Taylor-Ulitovsky technique.
- Characterization of its magnetic properties by Vibrant Sample Magnetometer (VSM) and Kerr Magnetometry techniques.
- Characterization of its structural properties by X-Ray Diffraction (XRD).

_		
$D_{II}$	nı	ications
гυ		เบลเบนเร

#### **PUBLISHED**

Lafuente-Arroyo S., Maldonado-Bascón S., Delgado-Mena D., **Gutiérrez-Alvarez C**, Acevedo-Rodríguez F.J., Multisensory Integration for Topological Indoor Localization of Mobile Robots in Complex Symmetrical Environments, in Expert Systems with Applications, 2023.

**Gutiérrez-Alvarez C**, Ríos-Navarro P., Flor-Rodríguez-Rabadán R., Acevedo-Rodríguez F.J., López-Sastre R.J., Evaluation of Visual Semantic Navigation Models in Real Robots, in IROS Late Breaking Results, 2023.

**Gutiérrez-Alvarez C**, Hernández García S, Nasri N, Cuesta-Infante Alfredo, López-Sastre RJ, Towards Clear Evaluation of Robotic Visual Semantic Navigation, in ICARA, 2023.

Nasri N, López-Sastre RJ, Pacheco-da-Costa S, Fernández-Munilla I, **Gutiérrez-Álvarez C**, Pousada-García T, Acevedo-Rodríguez FJ, Maldonado-Bascón S. Assistive Robot with an Al-Based Application for the Reinforcement of Activities of Daily Living: Technical Validation with Users Affected by Neurodevelopmental Disorders. Applied Sciences. 2022; 12(19):9566.

## **PREPRINTS**

**Gutiérrez-Alvarez C**, Ríos-Navarro P., Flor-Rodríguez-Rabadán R., Acevedo-Rodríguez F.J., López-Sastre R.J., Visual Semantic Navigation with Real Robots. arXiv 2023.

	res	$\sim$	+	 $\sim$	~
$\boldsymbol{r}$	$\sim$	$\omega$	114	 (1)	1

#### **CONTRIBUTED PRESENTATIONS**

**Gutiérrez-Álvarez, C**, Ríos-Navarro P., Flor-Rodríguez-Rabadán R., Acevedo-Rodríguez F.J., López-Sastre R.J., Evaluation of Visual Semantic Navigation Models in Real Robots. Poster and oral presentation: IROS 2023, Detroit, Michigan.

**Gutiérrez-Alvarez C**, Hernández García S, Nasri N, Cuesta-Infante Alfredo, López-Sastre RJ, Towards Clear Evaluation of Robotic Visual Semantic Navigation, in ICARA 2023, Abu Dhabi, United Arab Emirates.

**Gutiérrez-Álvarez, C**, Flor-Rodríguez-Rabadán R., Acevedo-Rodríguez F.J., López-Sastre R.J., Kanezaki.A, OffNav: Offline Reinforcement Learning for Visual Semantic Navigation. Late breaking results at ICRA 2024, Yokohama, Japan.

**Gutiérrez-Álvarez, C**, Flor-Rodríguez-Rabadán R., Acevedo-Rodríguez F.J., López-Sastre R.J., Kanezaki.A, OffNav: Offline Reinforcement Learning for Visual Semantic Navigation. Poster presentation at Human-aligned Reinforcement Learning for Autonomous Agents and Robots Workshop, ICRA 2024, Yokohama, Japan.

## SEMINARS AND WORKSHOPS

**Summer 2023**. Basics of Robotic Navigation. Seminar at Axpe Consulting, Madrid, Spain.

**Summer 2024**. *Reinforcement Learning para la robótica*. Workshop at Msc in Telecommunications Engineering, University of Alcalá, Madrid, Spain.

# INVITED TALKS

**Spring 2023**. Abro Micro: Inteligencia artificial e interpretación de conferencias. Podcast. Madrid, Spain.

Teaching	Experience	
Fall 2023	Circuits Theory, Teaching Assistant at University of Alcalá, Madrid.	
Mentorin	g	
2023-2024	<b>Alejandro Martín Sánchez</b> , BSc in Computer Science, University of Alcalá. Honors in final BSc project.	
Awards, F	Fellowships, & Grants	
2021	FPI Graduate Research Fellowship, Spanish Science Ministry	109.070€
Outreach	& Professional Development	

# **CERTIFICATIONS**

- 2024 Deep Reinforcement Learning Course, Hugging Face.
- 2021 Certified Machine Learning Specialty, Amazon Web Services.
- 2020 Certified Cloud Practitioner, Amazon Web Services.
- 2020 **TensorFlow Developer Certification**, Coursera.
- 2019 **Deep Learning Specialization**, Coursera.

## PEER REVIEW REVISOR

- 2024 Expert Systems with Applications, ESWA.
- 2023 Computer Vision and Pattern Recognition, CVPR.
- 2023 International Conference on Learning Representations, ICLR.